NOM02A4-AG01G

200DPI Contact Image Sensor Module

ON Semiconductor®

Description

The NOM02A4−AG01G contact image sensor (CIS) module integrates a green LED light source, lens and image sensor in a compact housing. The module is designed for document scanning, mark reading, gaming and office automation equipment applications and is suitable for scanning documents up to 216 mm wide. An analog video output achieves a scanning rate of 1.728 ms/line. The NOM02A4−AG01G module employs proprietary CMOS image sensing technology from ON Semiconductor to achieve high−speed performance and high sensitivity.

Features

- Light Source, Lens and Sensor are Integrated Into a Single Module
- 216 mm Scanning Width at 7.9 dots per mm Resolution
- 1.728 msec/Line Scanning Speed @ 1.0 MHz Pixel Rate
- Analog Video Output
- Supports A4 Paper Size at up to 15 Pages per Minute
- Green LED Light Source
- Wide Dynamic Range
- Compact 232.1 mm x 19.2 mm x 13.7 mm Module Housing
- Low Power
- Light Weight 2.1 oz Packaging
- These Devices are Pb−Free, Halogen Free/BFR Free and are RoHS Compliant

Applications

- Gaming Machines
- Fax Machines and Document Scanning
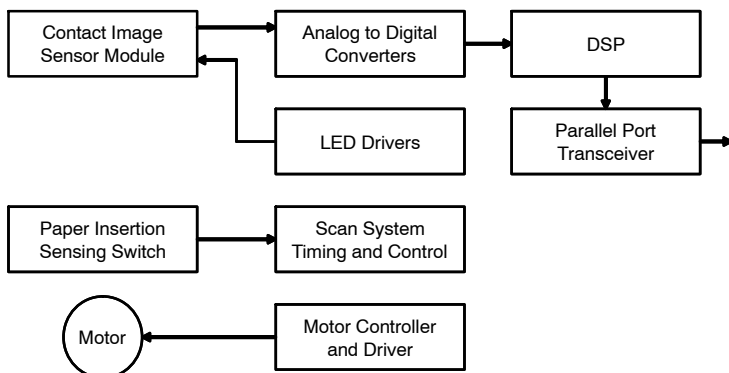- Mark Readers Including Balloting and Test Scoring
- Office Automation Equipment

IMAGE SENSOR MODULE A4
CASE MODAC

MARKING DIAGRAM

NOM02A4−AG01G

YYMMSSSSSS

YY	= Year
MM	= Month
SSSSSS	= Serial Number
G	= Pb−Free Package

CONNECTOR PIN ASSIGNMENT

VOUT	GND	VDD	VSS	GND	SP	GND	CP	GLED	VLED
1	2	3	4	5	6	7	8	9	10
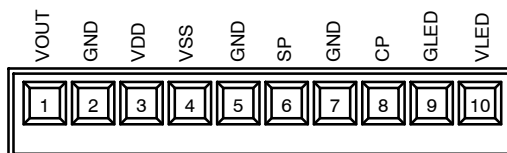
ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 2 of this data sheet.

Figure 1. Typical Scanner Application

NOM02A4−AG01G

Table 1. ORDERING INFORMATION

Part Number	Package	Shipping Configuration
NOM02A4−AG01G	(Pb−free)	100 per packing carton
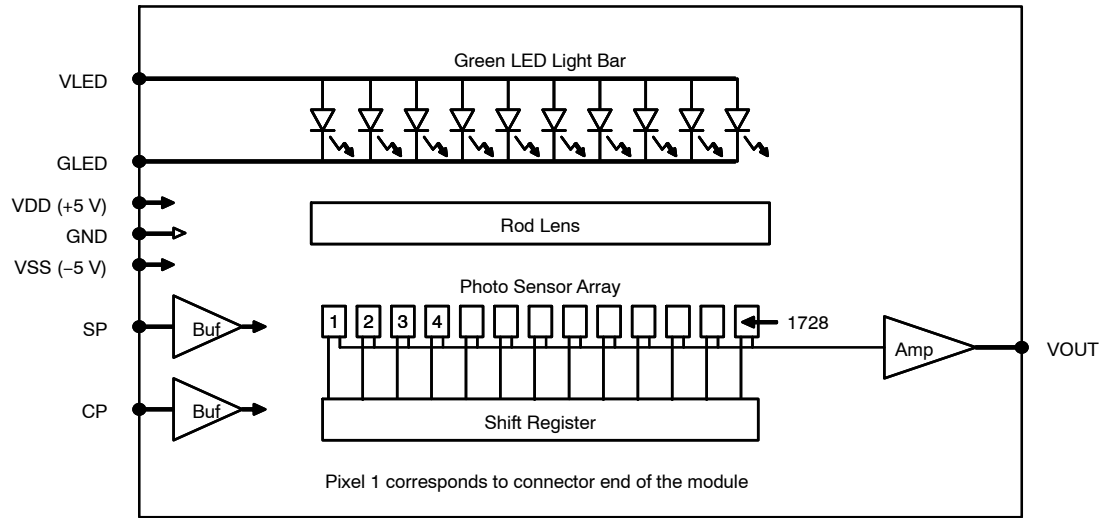
Figure 2. Simplified Block Diagram

Table 2. PIN FUNCTION DESCRIPTION

Pin	Pin Name	Description
1	VOUT	Analog Video Output
2	GND	Ground
3	VDD	+5 V power supply
4	VSS	−5 V to −12 V power supply
5	GND	Ground
6	SP	Shift register start pulse
7	GND	Ground
8	CP	Sampling clock pulse
9	GLED	Ground for the LED light source
10	VLED	Power supply for the LED light source

Table 3. ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Value	Unit
Power supply voltage	V_{DD}	7	V
	V_{SS}	−15	V
	V_{LED}	6	V
Power supply current	I_{LED}	600	mA
Input voltage range for SP, CP	V_{in}	−0.5 to V_{DD} + 0.5	V
Storage Temperature	T_{STG}	−20 to 75	°C
Storage Humidity, Non−Condensing	H_{STG}	10 to 90	%
ESD Capability, Contact Discharge (Note 1)	ESD_{HBM}	± 2	kV

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.
1. This module assembly has been ESD tested to IEC61000−4−2 (HBM) Contact Discharge

Table 4. RECOMMENDED OPERATING RANGES (Unless otherwise specified, these specifications apply T_A = 25°C) (Note 2)

Parameter	Symbol	Min	Typ	Max	Unit
Power supply voltage (Note 3)	V_{DD}	4.5	5	5.5	V
	V_{SS}	−12	−5	−4.5	V
	V_{LED}	4.5	5	5.5	V
Power supply current	I_{DD}	53	60	67	mA
	I_{SS}	5.0	6.0	7.0	mA
	I_{LED}	400	450	500	mA
Low level input voltage for SP, CP	V_{IL}	0	0	0.8	V
High level input voltage for SP, CP	V_{IH}	4.5	5.0	V_{DD} + 0.3	V
Line scanning rate (Note 4)	T_{int}	6.91	1.728	0.864	ms
Clock frequency (Note 5)	f	0.25	1.0	2.0	MHz
Clock period	t_o	0.5	1.0	4.0	μs
Clock pulse width (Note 6)	t_w	125	250	1000	ns
Clock pulse high duty cycle	DC_{CP}	20	25	60	%
Start pulse width (Note 6)	t_{wSP}	150	180	480	ns
Start pulse setup time	t_{su}	20			ns
Start pulse hold time	t_h	20			ns
Prohibit crossing time (Note 7)	t_{prh}	20			ns
Clock to Video output propagation delay rising	t_{pcor}	150			ns
Clock to Video output propagation delay falling	t_{pcof}	20			ns
Operating Temperature	T_{op}	0		50	°C
Operating Humidity, Non−Condensing	H_{op}	10		60	%

2. Refer to Figure 3 for more information on AC characteristics
3. V_{LED} directly affects illumination intensity, which directly affects V_{OUT}.
4. T_{int} is the line scanning rate or integration time. T_{int} is determined by the interval between two start pulses. The clock is proportional to T_{int}.
5. Main clock frequency (f) corresponds to the video sampling frequency.
6. Min, Typ, Max specifications reflect operation at the corresponding Min, Typ, Max clock frequency.
7. Prohibit crossing time is to insure that two start pulses are not supplied in the same scan line time. SP may only be active high during one falling edge of CP for any given scan.

Table 5. PHYSICAL SPECIFICATIONS

Parameter	Symbol	Typ	Unit
Scan width	PD_w	216	mm
Number of Photo Detector Arrays	PDA_n	27	arrays
Number of Photo Detectors	PD_n	1728	elements

Table 6. PHYSICAL CHARACTERISTICS

Parameter	Symbol	Min	Typ	Max	Unit
Pixel pitch	PD_{sp}		125		μm
Inter−array spacing	PDA_{sp}	150	180	210	μm
Inter−array vertical alignment	PDA_{vxp}	−40	0	40	μm
Green LED peak wavelength	λ_p	561		575	nm

Table 7. ELECTRO−OPTICAL CHARACTERISTICS TEST CONDITIONS

Parameter	Symbol	Value	Unit
Power supply voltage	V_{DD}	5.0	V
	V_{SS}	−5.0	V
	V_{LED}	5.0	V
Clock frequency	f	1.0	MHz
Clock pulse high duty cycle	DC_{CP}	25	%
Line scanning rate	T_{int}	1.728	ms
LED arrays pulsed time on (Note 8)	LED_Ton	26	ms
LED arrays pulsed time off (Note 8)	LED_Toff	356	ms
Operating Temperature	T_{op}	25	°C

8. Production tested with pulsing LEDs.

Table 8. ELECTRO−OPTICAL CHARACTERISTICS (Unless otherwise specified, these specifications were achieved with the test conditions defined in Table 7)

Parameter	Symbol	Min	Typ	Max	Unit
Bright analog output voltage (Note 9)	V_{pavg}	0.9	1.0	1.1	V
Bright output non−uniformity (Note 10)	U_p	−30		30	%
Bright output non−uniformity total (Note 11)	U_{ptotal}			60	%
Adjacent pixel non−uniformity (Note 12)	U_{padj}			25	%
Dark output voltage (Note 13)	V_d			200	mV
Dark non−uniformity (Note 14)	U_d			200	mV
Modulation transfer function at 50 line pairs per in (lp/in) (Note 15)	MTF_{50}	40			%
Modulation transfer function at 100 line pairs per in (lp/in) (Notes 15, 16)	MTF_{100}	20			%

9. $V_{pavg} = \Sigma\, V_{p(n)}/1728$, where
   V_p is the pixel amplitude value of V_{OUT} for a bright signal defined as a white document with LEDs turned on,
   n is the sequential pixel number in one scan line.
10. $U_p = [(V_{pmax} - V_{pavg})/V_{pavg}]$ x 100%, or $[V_{pavg} - V_{pmin})/V_{pavg}]$ x 100%, whichever is greater, where
    V_{pmax} is the maximum pixel voltage of any pixel at full bright
    V_{pmin} is the minimum pixel voltage of any pixel at full bright
11. $U_{ptotal} = [(V_{pmax} - V_{pmin})/V_{pavg}]$ x 100%,
12. $U_{padj} = MAX\,[\,|\,(V_{p(n)} - V_{p(n+1)}\,|\,/\,V_{p(n)}]$ x 100%, where
    U_{padj} is the nonuniformity in percent between adjacent pixels for a bright background
13. V_d is the pixel amplitude value of V_{OUT} for a dark signal defined as a black document with LEDs turned off
14. $U_d = V_{dmax} - V_{dmin}$, where
    V_{dmax} is the maximum pixel voltage of any dark pixel with the LEDs turned off
    V_{dmin} is the minimum pixel voltage of any dark pixel with the LEDs turned off
15. $MTF = [(V_{max} - V_{min})/(V_{max} + V_{min})]$ x 100%, where
    V_{max} is the maximum output voltage at the specified line pairs per inch (lp/in)
    V_{min} is the minimum output voltage at the specified lp/in
16. For information only.
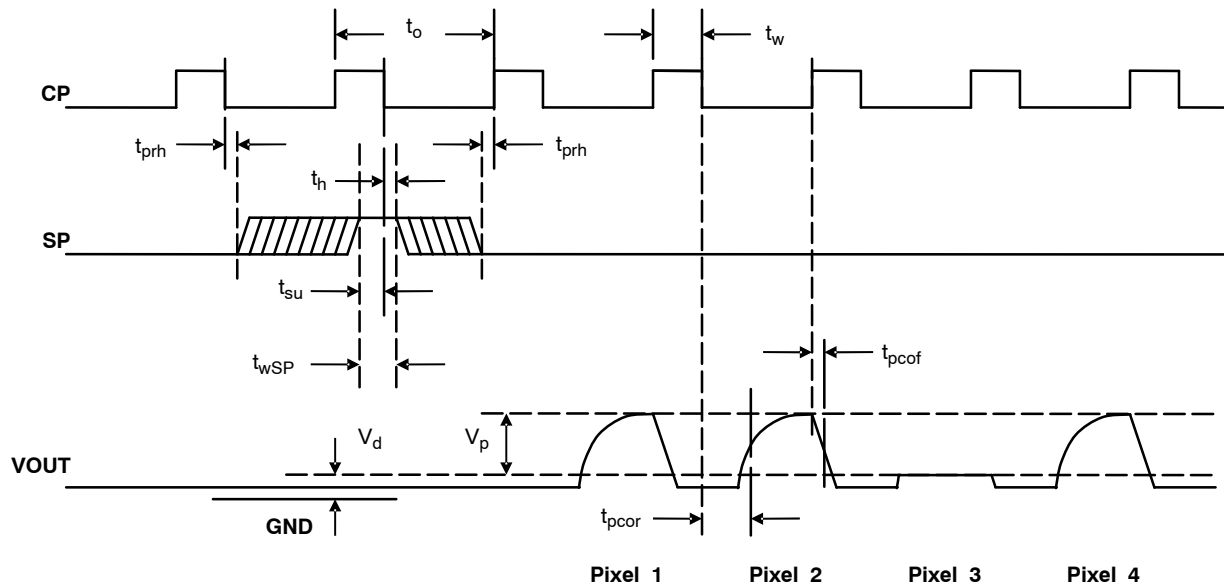
Figure 3. Timing Diagram

DESCRIPTION OF OPERATION

Functional Description

The NOM02A4−AG01G module consists of 27 contact image sensors, each with 64 pixel elements, that are cascaded to provide 1728 photo−detectors with their associated multiplex switches and double−buffered digital shift register that controls its sequential readout. A buffer amplifies the video pixels from the image sensors and output the analog video signal of the module as shown in Figure 2. In operation, the sensors produce an analog image pixel signal (or video signal) proportional to the exposure on the corresponding picture elements on the document. The VOUT signal outputs 1728 pixels for each scan line. The first bit shifted out from VOUT during each scan represents the first pixel on the connector end of the module.

A pictorial of the NOM02A4−AG01G cross section view is shown in Figure 4. Mounted in the module is a one−to−one graded−index micro lens array that focuses the scanned document image onto the sensing plane. Illumination is accomplished by means of an integrated LED light source. All components are housed in a small plastic housing, which has a glass cover. The top surface of the glass acts as the focal point for the object being scanned and protects the imaging array, micro lens assembly and LED light source from dust.
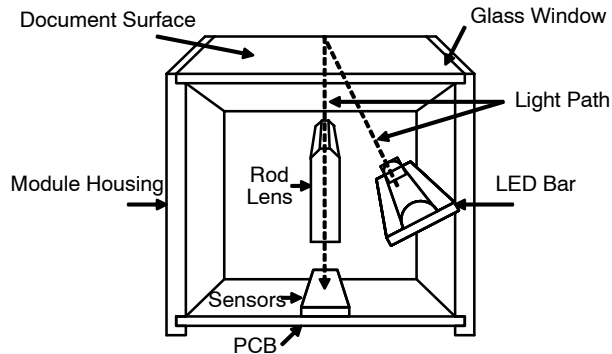
Figure 4. Module Cross Section View

Connector Pin Out Description

Connections to the module are via a 2.4x14.50mm 10−pin connector (ECE part number EBW−PK23−P010L2−3Z) located at one end of the module as shown in the package drawing on page 8. The location of pin number 1 is indicated on the package drawing.

Scanner Applications

A typical use of the NOM02A4−AG01G module in scanner applications is shown in Figure 6. The document to be digitized is fed into the scanner where a sensor detects its presence. The scanner then operates the motor to move the paper under the contact image sensor module. The module illuminates the paper with internal LEDs and the image sensor pixel array detects the amount of reflected light and simultaneously measures a full line of pixels which are sampled and transferred to a FIFO for storage and conversion to a parallel output format. Once the pixel line is processed, the motor advances the paper and the next scan line is captured.
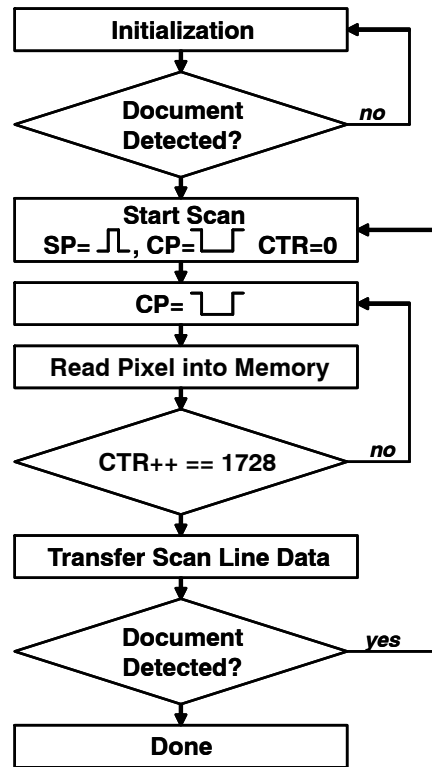
Figure 5. Typical Scanner Algorithm

Figure 5 outlines the basic steps in the scanner control sequence. First the circuits are initialized and the scanner waits for a document to be detected, usually by a paper sensing switch. Then a start pulse and clock pulse are supplied to capture a line image. At the next clock pulse the first pixel value appears on the output. The pixel can be stored in a local line buffer memory. Subsequent clocks cause the remaining pixels to be shifted out and stored in the line buffer. Once the complete line has been shifted out it can be transferred to the host application and the system advances the paper and the line scan process repeats until the paper sensing switch indicates the document has passed completely through the scanner.

Device Marking and Barcode Description

Each module is marked with a tag that contains the part number, a number combining the manufacturing date code and serial number and a barcode. The barcode presents the date code and serial number in Interleave 2 of 5 barcode format as follows

$$YYMMSSSSSS$$

where
YY is the year,
MM is the month, and
SSSSSS is the serial number.

Glass Lens Care

Precautions should be taken to avoid scratching or touching the glass lens. The glass lens may be cleaned with alcohol.
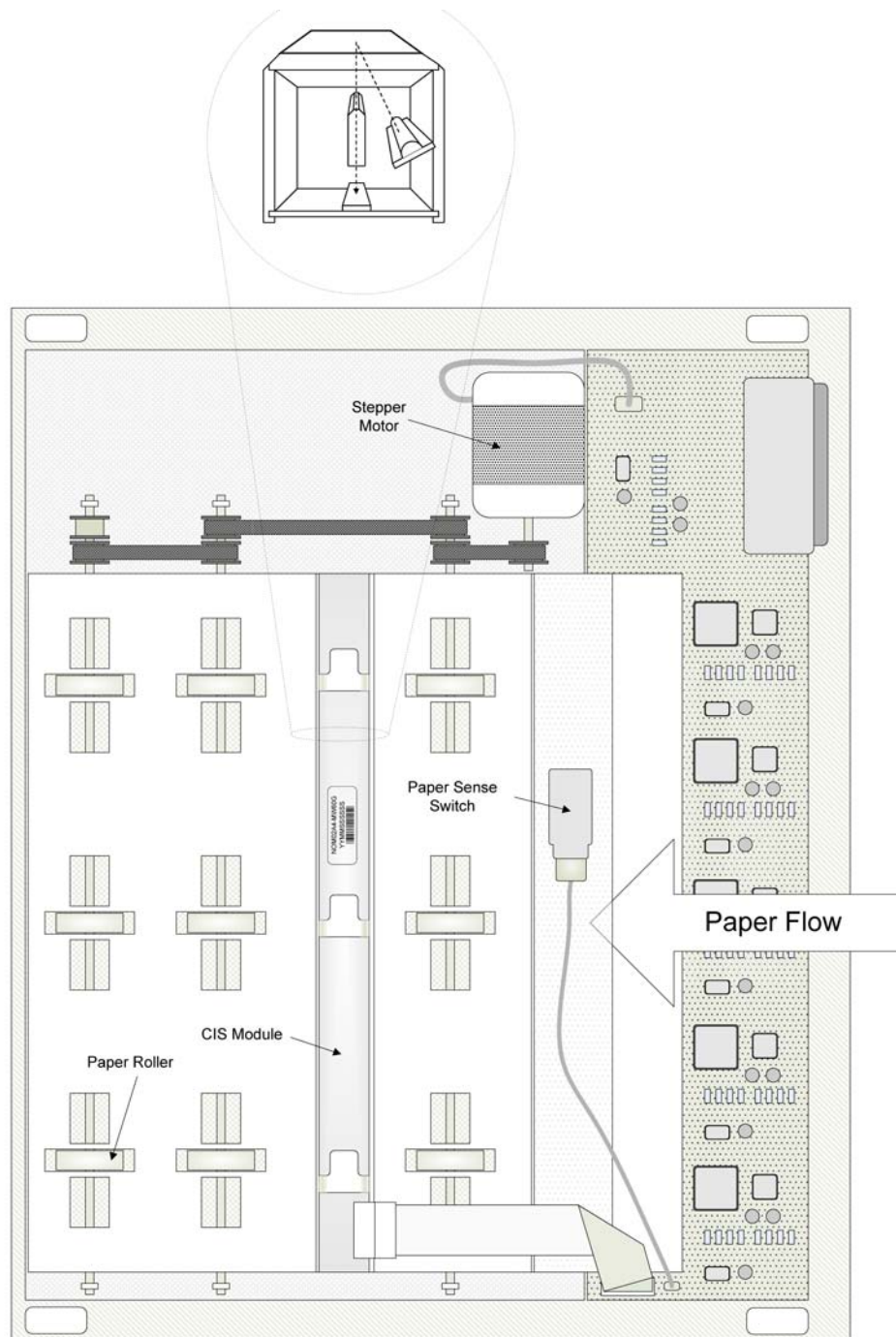
Figure 6. Typical Scanner Assembly

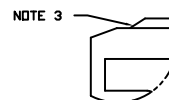## IMAGE SENSOR MODULE
CASE MODAC
ISSUE A

DATE 11 MAY 2010

NOTE 3

DETAIL A
8X SCALE

NOTE 9

K
NOTE 10

D1

NOTE 6

B2

NOTE 6

READ LINE

NOTE 6

NOTE 6

D

DETAIL A

B1

B

C

NOTE 7

0.10

A2

A

A1

L

NOTE 4

DETAIL B

E

NOTE 4

END VIEW
4X SCALE

F

F

PIN 1
NOTE 5

H

H

TAG

3X J
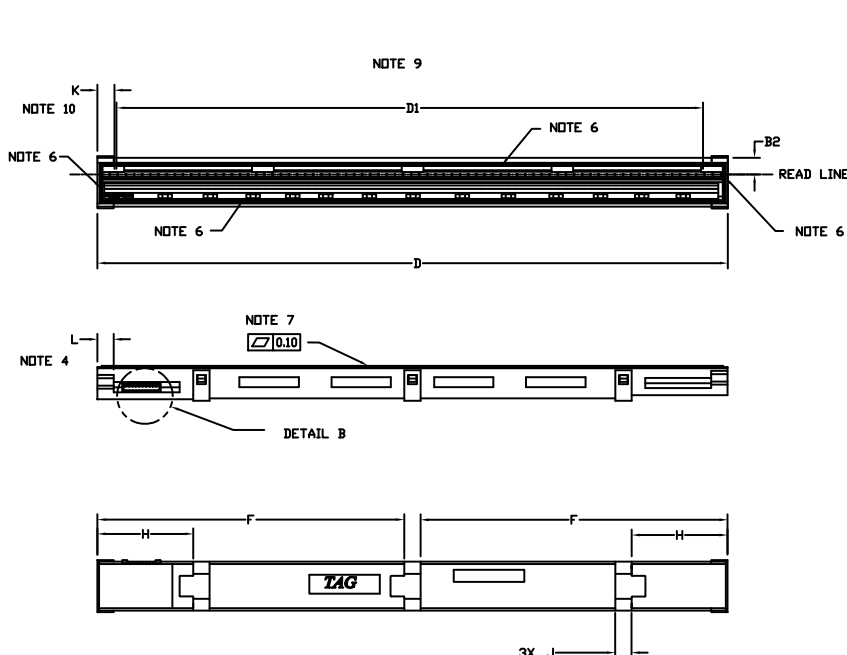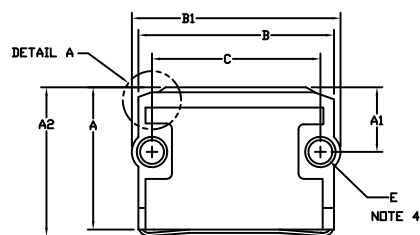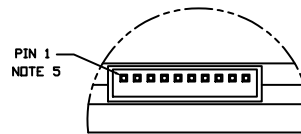
DETAIL B
4X SCALE

NOTES:
1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. LEADING EDGE OF THE APPROACH ANGLE ON THE GLASS IS LOWER THAN THE TOP OF THE HOUSING.
4. BORE DEPTH IS 6.0 WITH A 0.3 LEAD–IN CHAMFER.
5. PIN HEADER, MODEL NUMBER EBW–PK23–P010L2–3Z, 1X10 PIN, PITCH 1.25.
6. GLASS IS GLUED ON ALL 4 SIDES.
7. GLASS THICKNESS IS 1.85.
8. USE M2.3 SELF TAPPING SCREWS FOR MOUNTING. TORQUE SCREWS BETWEEN 1.80 KGF–CM AND 2.00 KGF–CM.
9. DIMENSION D1 DENOTES THE SCAN LENGTH.
10. DIMENSION K DENOTES THE POSITION OF THE FIRST PIXEL.

DIM	MILLIMETERS	
	MIN	MAX
A	12.60	13.60
A1	5.45	6.45
A2	13.20	14.20
B	17.70	18.30
B1	18.90	19.50
B2	5.50	6.50
C	15.40	15.60
D	231.60	232.60
D1	216.00 REF	
E	2.10	2.30
F	112.50	113.50
H	34.80	35.80
J	5.70	6.30
K	5.30	7.30
L	6.00 REF	

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DESCRIPTION:	IMAGE SENSOR MODULE		PAGE 1 OF 1

ADDITIONAL INFORMATION

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